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1
2 [Audio]
3 allowHardwareStreams=1 ; try to use hardware streams if available
4 devMicrophoneAPI=1 ; 0 = None, 1 = DirectSound
5 devSPCCAPI=1 ; 0 = None, 1 = DirectSound
6 devSpeakerAPI=1 ; 0 = None, 1 = DirectSound
7 devVoiceChatAPI=1 ; 0 = None, 1 = DirectSound
8 dimensions=2 ; 1 = mono, 2 = stereo, 3 = surround
9 loudnessAmbient=-17.100000 ; Volume adjustment for ambient noise in dB
10 loudnessCrash=-8.300000 ; Volume adjustment for scrapes and crashes
    in dB
11 loudnessEngine=-9.000000 ; Volume adjustment for engines in dB
12 loudnessReplay=0.000000 ; Volume adjustment for overall replay
    volume versus driving volume in dB
13 loudnessSPCC=-40.000000 ; Volume adjustment for spotter noise in dB
14 loudnessTires=-9.000000 ; Volume adjustment for tires in dB
15 loudnessVoiceChat=-15.000000 ; Volume adjustment for voice chat noise in
    dB
16 loudnessWind=-5.400000 ; Volume adjustment for wind in dB
17 masterVolumedB=0.000000 ; Master volume adjustment in dB, range is
    -120 dB to 0 dB
18 micAlwaysActive=1 ; Set this to 0 if your graphics stutter
    when a microphone is configured, but doing so may cause worse stutters while recording
    for voice chat
19 mute_WhenFocusLost=0 ; set this to 0 to hear sim sounds when
    another program has the keyboard focus
20 numSoundStreams=-1 ; Maximum number of audible sounds
21 overrideSpccRate=0 ; If set to 1, the spotter sounds will be
    resampled to play back at the general sample rate. This is a compatibility fix for
    sound cards with limited playback rates and is not recommended for general use.
22 overrideVoiceChatRate=0 ; If set to 1, void chat will be resampled
    to play back at the general sample rate. This is a compatibility fix for sound cards
    with limited playback rates and is not recommended for general use.
23 rotateWithHeadset=1 ; 0 = no, 1 = rotate microphone with VR
    headset movement
24 sampleRate=22050 ; sample rate to run sound system at
25 stereoStreamInSurroundBalance=1.000000 ; stereo streams (the engine) in surround
    mode need a system specific adjustment to match volume with surround streams
26 voiceChatEnabled=1 ; Enable or Disable Voice Chat.
27 voiceChatEnabledWhileDriving=1 ; Enable voice chat while driving.
28 voiceChatMuted=0 ; Mute voice chat - overrides
    voiceChatVolume.
29 voiceChatNotificationStyle=2 ; Voice chat notification style.
30 voiceChatSaveToReplay=2 ; 0=All channels, 1=All but user-created
    channels, 2=All but user-created and @TEAM, 3=None
31
32 [Autochat Messages]
33 AutoChatStr1=Pitting In$ ; Auto chat message, use $ at the end to
    auto transmit without hitting enter
34 AutoChatStr10=Shut up, crazy fool!$ ; Auto chat message
35 AutoChatStr11=#lf rf lr rr ws fuel 500g$ ; Auto chat message
36 AutoChatStr12=#rf rr$ ; Auto chat message
37 AutoChatStr13=#lf rf lr rr$ ; Auto chat message
38 AutoChatStr14=#fuel 2g$ ; Auto chat message
39 AutoChatStr15=#fuel 10g$ ; Auto chat message
40 AutoChatStr2=Pitting Out$ ; Auto chat message,
41 AutoChatStr3=Pass Left$ ; Auto chat message
42 AutoChatStr4=Pass Right$ ; Auto chat message
43 AutoChatStr5=Sorry!$ ; Auto chat message
44 AutoChatStr6=Thanks!$ ; Auto chat message
45 AutoChatStr7=You're welcome$ ; Auto chat message
46 AutoChatStr8=Ok$ ; Auto chat message
47 AutoChatStr9=Quit yo Jibber-jabber!$ ; Auto chat message
48
49 [CamTool]
50 autoShotSelection=1 ; Automatically switch cameras based on
    shot quality
51 camTempEdit=0 ; don't save edits to cameras, useful for
    'live' edits

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52  ctrlIncAccel=1 ; use acceleration when adjusting cameras
53  ctrlIncScalar=10.000000 ; scalar to use when selecting fast move mode
54  ctrlIncScalarApply=0 ; enable fast move mode (10x)
55  ctrlIncVal=1.000000 ; step size when adjusting cameras
56  focusIncALin=6.000000 ; adjust linearity of analog focus
   controls, 1 == linear, 6 == very nonlinear
57  focusIncAScalar=10.000000 ; adjust focus adjustment speed for analog
   controls
58  fovIncALin=4.000000 ; adjust linearity of analog FOV controls,
   1 == linear, 6 == very nonlinear
59  fovIncAScalar=20.000000 ; adjust FOV adjustment speed for analog
   controls
60  linearPanBlend=0.000000 ; 0.0 - pan slows down with increased zoom,
   1.0 - pan remains constant
61  rotIncALin=4.000000 ; adjust linearity of analog rotation
   (yaw,pitch,roll) controls, 1 == linear, 6 == very nonlinear
62  rotIncAScalar=4.000000 ; adjust rotation (yaw,pitch,roll)
   adjustment speed for analog controls
63  showCamMode=0 ; display cameras in world, 0-Live, 1-Wide,
   2-Front, 3-Side, 4-Top
64  transIncALin=4.000000 ; adjust linearity of analog translation
   (x,y,z) controls, 1 == linear, 6 == very nonlinear
65  transIncAScalar=4.000000 ; adjust translation (x,y,z) adjustment
   speed for analog controls
66
67  [Commercial]
68  SkipInvalidResults=0 ; In looping qualify, skip over results
   display if no valid lap time
69
70  [Drive Screen]
71  blackBox=2 ; Which black box to display
72  blackBoxPitStop=0 ; Which pit stop black box to display
73  resetCanExitCar=1 ; Does pressing <reset> exit the car while
   in the pit stall?
74  showRadioControls=1 ; Display the radio channel control while
   driving?
75  showSpeedGearControls=1 ; Display the Speed / Gear / Pedals / Wheel
   black box?
76  showSystemMeters=1 ; Display the FPS / Network black box?
77  showVideoTimer=0 ; Display a clock on the screen that can be
   used to synchronize live video with a replay
78  UIOffsetBottomPct=0 ; Shift bottom of UI up by specified percent
79
80  [External_Displays]
81  arxDisplayPack=ir_hud ; What display to show on the Logitech ARX
   client.
82  colorLEDHotKeysByType=1 ; Set to 0 to color all hotkey indicators
   the same color
83  enableLEDFlags=1 ; Set to 0 to turn off the flag animations
84  enableLEDHotKeys=1 ; Set to 0 to turn off the keyboard hotkey
   indicators
85  enableLEDShiftLights=1 ; Set to 0 to turn off the rpm shift
   indicator animations
86  enableLogitechARX=1 ; Enable Logitech ARX client to create a
   digital dash on your smartphone
87  enableLogitechLED=1 ; Animate the backlights on RGB gaming
   keyboards
88  phoneCanSteer=1 ; Allow phone device to act as a steering
   wheel
89
90  [Force Feedback]
91  allowXBoxOneOnWindows10=1 ; Set to 1 to talk to xbox one game pads on
   windows 10, warning the driver is buggy
92  alwaysRestartFX=0 ; Always restart force when updating it,
   set to true if wheel goes limp after a while
93  calibUsingRawData=0 ; Use raw joystick position over windows
   calibration data when detecting new joysticks
94  centerSpringPct=-1 ; Percent (0-100) of static centering
   spring force to apply, -1 is off. Not recommended for use.

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95 damperMode=0 ; Set damper effect type 0 = Damper 1 =
Inertia 2 = Friction
96 damperSaturation=10000 ; Set damper saturation from 0 to 10000
97 dampingSliderSetsFriction=1 ; True if damping slider adjust friction
effect, false to adjust wheels built in damping effect
98 debounceSeq_Ms=80 ; Add delay in Milliseconds to sequential
shifter to reduce double shifts
99 disableAutoCenter=1 ; Turn auto center off on all force
feedback devices
100 displayLinearInNm=1 ; Display the force level in peak Nm when
using the linear mode
101 enableFanatecWheelDisplay=1 ; Enable the use of Fanatec wheel displays
102 enableG27WheelDisplay=1 ; Enable use of shift indicators on the G27
and clones
103 enableHotPlug=1 ; Set to 0 to turn off usb hot plugging in
case you have usb disconnect issues
104 enableWheelDisplayBlink=1 ; Enable the display lights to blink when
at the rev limit
105 FFBUseSimpleMinForce=0 ; 0 - Use smoothed min force, 1 - use old
sharp min force
106 forceNoiseSuppression=0 ; Remove noisy joystick axis, even if they
are calibrated by hand
107 forceResetBeforeStartup=0 ; Force a reset of the whole FFB system
every time we create or destroy a FFB effect
108 initOnlyNewDevices=1 ; Set to 0 to force all devices to
reinitialize when a device change is detected
109 invertFFBForce=0 ; Reverse the force feedback effects, if
your wheel is spinning the wrong way
110 reinitFanatecWheelDisplay=0 ; reinitialize the fanatec wheel display
when reconnecting devices this may cause issues
111 seperateXBox360Triggers=1 ; Set to 1 to seperate the Xbox 360
joystick triggers into there own axes
112 steerAverageSteeringTorque=0 ; True averages 360 Hz data down to 60 Hz,
false uses last sample
113 steeringBumpStop_Deg=15.000000 ; degrees into bump stop before max force
114 steeringDampingFactor=0.050000 ; Damping factor adjust down if damping
becomes unstable, default to 0.05
115 steeringDampingMaxPercent=0.000000 ; Maximum amount of damping to apply,
adjust this to set damping level, values between 0.05 and 0.2 are best, overridden by
damping slider
116 steeringDampingParkedMaxPercent=0.050000 ; Maximum amount of damping to apply when
parked, adjust this to reduce wheel oscilation when parked, values between 0.05 and
0.30 are best
117 steeringFFBSmooth=1.000000 ; Percent of current FFB force to use vs
average force, 1.0 = no average 0.001 = max average
118 steeringForceParkedPct=0.500000 ; Reduce FFB force by percent when parked,
to help reduce oscilations
119
120 [Graphics]
121 DriveUIFullScreen=0 ; Let triple headed driving UI expand to
fill full display
122 DriveUITransparency=0.720000 ; Adjust driving UI transparency up or down
123 forceCrowdVisible=0 ; Force the crowd in the grandstand to show
up on practice and qualify sessions.
124 forceVisibleWhenMove=0 ; Force all movable controls to become
visible when moving UI elements
125 hideCarNum=0 ; Hide car numbers and other decals in test
sessions, so you can paint your own versions.
126 KeepUIHiddenOnFocus=0 ; If set to 1 then the UI can only be
enabled with the space bar and not a mouse click
127 maxParticleThreads=6 ; #workers (0 to 6)
128 NotifyOfDirtRequirements=1 ; Should the Session screen notify about
too-low graphics settings?
129 particleThreadPriorityAdjust=0 ; belowNormal=-1 normal=0 aboveNormal=1
130 reduceFramerate_WhenFocusLost=0 ; set this to 0 to maintain full framerate
when another program has the keyboard focus
131 serverTransmitMaxCars=27 ; Limit number of cars transmitted to
client (values from 10 to 64)
132 SessionUIFullScreen=0 ; Let triple headed session UI expand to

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fill full display
133 SessionUITransparency=0.720000 ; Adjust session UI transparency up or down
134
135 [Graphics DX11]
136 border=0 ; window border?
137 browserForceWindowedMode=1 ; force the browser windowed (if sim
sessions are full-screen)
138 browserIsMaximized=0 ; browser Window is maximized in windowed
mode
139 browserWindowedHeight=864 ; Browser windowed mode height
140 browserWindowedWidth=1536 ; Browser windowed mode width
141 browserWindowedXPos=192 ; Browser Window top left corner in
windowed mode
142 browserWindowedYPos=108 ; Browser Window top left corner in
windowed mode
143 deviceId=0 ; which adapter
144 displayRotateMode=1 ; 0-auto, 1-landscape, 2-landscape inv,
3-portrait, 4-portrait inv
145 fullScreen=1 ; fullscreen?
146 fullScreenDepth=32 ; Color depth
147 fullScreenHeight=1080 ; full screen Window's height
148 fullScreenWidth=1920 ; full screen Window's width
149 ModeScaling=0 ; 0=unspecified 1=centered 2=stretched
150 pixelRatio=1.000000 ; Full screen mode - Adjust for displays
with non-square pixels
151 pixelRatioWindowed=1.000000 ; Windowed mode - Adjust for displays with
non-square pixels
152 RefreshRate=143.996002 ; Refresh Rate
153 UseCoherentUI=0 ; Use Coherent UI?
154 windowedAlignment=0 ; windowed mode alignment: 0 - none, 1 -
center, 2 - top left
155 windowedHeight=1048 ; windowed mode height
156 windowedMaximized=0 ; Window is maximized in windowed mode
157 windowedWidth=1920 ; windowed mode width
158 windowedXPos=-7 ; Window top left corner in windowed mode
159 windowedYPos=0 ; Window top left corner in windowed mode
160
161 [Locale]
162 dateFormat=0 ; Ordering of month, day, year
163 systemOfMeasurement=0 ; System of measurement used
164
165 [Main Screen]
166 blackBox=-1 ; Which black box to display
167
168 [Misc]
169 garageAutoApply=1 ; automatically hit the apply button after
five seconds of inactivity.
170 irsdkAutoLogDisk=0 ; Automatically log disk telemetry when you
enter your car, this can fill up your disk!
171 irsdkEnableDisk=1 ; enable disk based telemetry
172 irsdkEnableMem=1 ; enable memory based telemetry
173 irsdkLog360Hz=0 ; Log some telemetry at 360 Hz rather than
at 60 Hz
174 irsdkLogSetup=1 ; Log the current setup to telemetry
175 showIncidentMessagesWhileDriving=1 ; Show Incident messages while driving
176 showJoinLeave=1 ; Show player join/leave messages
177 showSysMessagesWhileDriving=1 ; Show system messages while driving
178 showUserMessagesWhileDriving=1 ; Show user chat messages while driving
179
180 [Overlay]
181 EnableTicker=0 ; set to 1 to turn on ticker when session
UI is disabled
182
183 [Pit Service]
184 autoResetFastRepair=1 ; Automatically request fast repair service
once your vehicle exits pit road
185 autoResetPitBox=0 ; Automatically request full pit service
once your vehicle exits pit road
186

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187  [Replay]
188  askToSaveOnQuit=1 ; Ask to save the replay before quitting
    via the [Quit] button??
189  CPUUsageAtWhichToReducePlaybackRate=95 ; Realtime thread CPU usage at/above which
    to reduce play speed (0 disables)
190  CPUVsPlaySpeedCheckPeriod=2 ; Number of seconds between checks to see
    if play speed is chewing up too much CPU
191  maxFramesToSearchPerUpdate=2048 ; Maximum # of frames to search per update
192  noRpyCtrlsOnNumpad=0 ; Remove all default replay controls mapped
    to number pad
193  pauseReplayOnExit=0 ; Pause replay when exiting your car.
194  repeatedSearchDelay=400 ; Min milliseconds between successful
    long-search completions
195  replayPatchRemoteCars=1 ; update remote car positions in replay
    based on server data
196  spoolingEnabled=1 ; enable replay spooling?
197  spoolOnlyIfDiskFreeMB=1024 ; 0=don't check, otherwise must have this
    many MB free disk or spooling won't enable
198  spoolRecordingToDiry= ; If spooling recording, write tmp file
    into this directory
199  spoolTapeSizePct=25 ; % of allowed memory to use for the spool
    buffer (0=min,100=max)
200  spoolTmpFilesNamed=0 ; use different file names for each spooled
    .tmp file?
201
202  [SetupAutoLoad]
203  astonmartin_dbr9=0
204  audir8gt3=0
205  bmwz4gt3=0
206  c7vettedp=0
207  dallarair18=0
208  dirtstreetstock=1
209  formularenault20=0
210  fr500s=0
211  mclarenmp4=0
212  mercedesamgg3=0
213  mx5_mx52016=0
214  nissangtpzxt=0
215  porsche911cup=0
216  porsche919=0
217  porsche991rsr=0
218  radical_sr8=0
219  rufrt12r_track=0
220  subaruwrxsti=0
221  trucks_silverado=0
222  v8supercars_ford2014=1
223  v8supercars_holden2014=0
224
225  [SPCC]
226  carLowHiAtStart=0 ; If true enable car low_high calls as soon
    as green flag is out
227  carLowHiPadding=0.250000 ; How much clearance, front and back in
    meters, to give a car before reporting it as clear
228  enabled=0 ; Is the spotter enabled at all?
229  muteSpotterIfLive=1 ; Mute your spotter if you have a live
    spotter already spotting for you
230  reduceVerbosityIfLive=1 ; Reduce the spotters chattiness if you
    have a live spotter already spotting for you
231  reportLapsEnabled=0 ; Enable spotter calls out lap times
232  reportLapsMinute=1 ; Call out the minute when calling the time
233  reportLapsMode_n=0 ; Spotter calls out lap times, 0 - time, 1
    - avg speed
234  reportLapsPrecision=3 ; How much precision to display lap times
    with
235  text=1 ; Does the spotter display text messages?
236  topic_mask=0
237  verbosity=1 ; How chatty is the spotter?
238  voice=1 ; Does the spotter talk to you?
239  voicePack= ; Voice pack for spotter, leave blank for

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default spotter
240
241 [spectator]
242 defaultShotMode=3 ; default target to focus on when spectating
243
244 [SplitsDeltas]
245 comparisonLapFileName= ; User specified split delta file used for
comparison
246 deltaBarDisplayDeltabar=1 ; Show the delta bar when displaying split
time or ghost car
247 deltaBarDisplayLaps=0 ; Reference lap to compare against while
driving, 0 disables the reference lap.
248 deltaBarDisplayLapsTA=1 ; Reference lap to compare against while
driving in Time Attack, 0 disables the reference lap.
249 deltaBarDisplayRefCar=1 ; If 1 display a reference car on track
that you can race against. This may not be enabled in all sessions.
250 deltaBarRangeOval=0.500000 ; delta bar range as +/- N seconds when at
an oval
251 deltaBarRangeRoad=2.000000 ; delta bar range as +/- N seconds when at
a road course
252 disableAtRaceStart=1 ; If 1 disable the split time at start of
race, you can manually enable it again later.
253 fadeGhostCarWhenClose=1 ; If 1 then increase the ghost car
transparency as you drive near it.
254 ghostCarOffsetSec=0.000000 ; How many seconds to offset the ghost car
by.
255 ghostCarTransp=0.350000 ; Set level of transparency for ghost car
(reference lap car).
256
257 [TiltDrive]
258 tiltInvertX=0 ; Invert the tilt steering axis
259 tiltInvertY=0 ; Invert the tilt gas/brake axis
260 tiltMaxAngleX=90.000000 ; changes tilt sensitivity for the steering
axis
261 tiltMaxAngleY=30.000000 ; changes tilt sensitivity for the
gas/brake axis
262 tiltSensorEnable=1 ; Set to false to stop detection of tilt
sensors
263 useOrientationSensor=1 ; Choose between the orientation sensor or
the accelerometer
264
265 [TouchDrive]
266 enableMouseWhileDriving=1 ; Enable the mouse controls in the driving
screen
267 touchCenterOnFirstTouchX=0 ; Center x of control set by first touch
268 touchCenterOnFirstTouchY=1 ; Center y of control set by first touch
269 touchComboHeight=0.150000 ; Height, as a percent of screen width, of
the center combination touch drive input
270 touchComboUseSingleCursor=1 ; use a single cursor on the x/y combo
control
271 touchComboWidth=0.400000 ; Width, as a percent of screen width, of
the center combination touch drive input
272 touchFalloff=0.016000 ; How fast the touch control will return to
its neutral setting once released
273 touchLockMouseOnClick=1 ; click once to activate mouse driving
control, click again to release it
274 touchSideEdgeOffset=0.020000 ; How close to the edge of the display are
the left/right touch driving input, when using a horizontal orientation
275 touchSideGasIsVertical=1 ; Orient the (right) gas/brake input zone
vertically or horizontally
276 touchSideHeight=0.150000 ; Height, as a percent of screen width, of
the left/right touch drive inputs, when using vert orientation
277 touchSideHideOnMouse=1 ; hide the side controls when touch not
active
278 touchSideSteeringIsVertical=0 ; Orient the (left) steering input zone
vertically or horizontally
279 touchSideWidth=0.200000 ; Width, as a percent of screen width, of
the left/right touch drive inputs, when using a horizontal orientation
280 touchUseMouseRelativeMode=1 ; If true, then use a relative mouse mode,

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otherwise use absolute
281
282 [UIOffsetPos]
283 Fulldrv_SysInfo_X=10
284 Fulldrv_SysInfo_Y=-8
285 IDC_CT_GROUP_CAMERA_X=0
286 IDC_CT_GROUP_CAMERA_Y=0
287 IDC_FULLDRIVE_CONTROLS_SPEEDGEAR_X=588
288 IDC_FULLDRIVE_CONTROLS_SPEEDGEAR_Y=-1228
289 IDC_FULLDRV_BLACKBOXES_X=-1030
290 IDC_FULLDRV_BLACKBOXES_Y=-1226
291 IDC_FULLDRV_GRP_RADIO_TUNED_TO_X=587
292 IDC_FULLDRV_GRP_RADIO_TUNED_TO_Y=-1194
293 IDC_FULLDRV_INFO_X=20
294 IDC_FULLDRV_INFO_Y=411
295 IDC_FULLDRV_PITINFO_X=580
296 IDC_FULLDRV_PITINFO_Y=658
297 IDC_FULLDRV_SPLITS_X=-10
298 IDC_FULLDRV_SPLITS_Y=-320
299 IDC_SESSION_GRP_RADIO_TUNED_TO_X=-760
300 IDC_SESSION_GRP_RADIO_TUNED_TO_Y=-8
301 Session_BlackBoxes_X=477
302 Session_BlackBoxes_Y=-917
303 Session_SysInfo_X=-736
304 Session_SysInfo_Y=627
305
306 [Video]
307 screenshotFileFormat=0 ; Screenshot file format, 0 = png, 1 = jpg,
2 = bmp
308 vidCaptureEnable=0 ; Set to 0 to disable loading of video
capture module
309 videoCaptureMic=0 ; Set to 1 to capture audio from your
microphone
310 videoFileFrmt=0 ; Video encoder container, 0 = mp4, 1 =
wmv, 2 = avi, 3 = avi
311 videoFramerate=1 ; Video framerate, 0 = 60 fps, 1 = 30 fps
312 videoImgSize=2 ; Video max dimensions, 0 = auto,
1=1920x1080, 2=1280x720, 3=854x480
313
314 [View]
315 cockpitLookAngle=65.000000 ; Angle in degrees to rotate head when
looking left/right
316 cockpitLookDeadZone=0.050000 ; 0-1 value for deadzone. 0 is no deadzone.
317 cockpitLookDownAngle=20.000000 ; Angle in degrees to tilt head when
looking down
318 cockpitLookInstant=1 ; does digital look left/right/up/down
switch instantly, or transition smoothly?
319 cockpitLookSmoothingTime=0.055556 ; Time value (secs) used in joystick
smoothing
320 cockpitLookUpAngle=15.000000 ; Angle in degrees to tilt head when
looking up
321 DriverHeadHorizon=0.000000 ; Percent to allow the drivers head to stay
level with the horizon when the car tilts.
322 DriverHeadNoPitch=0.000000 ; Percent to allow the drivers head to stay
level with the horizon when the car pitches.
323 DriverHeadWobble=1.000000 ; Percent to allow the drivers head to
wobble when going over bumps.
324 driverHeightAdj=0.000000 ; Range -0.050m to 0.050m (approx. +/- 2
in.)
325 DriverRotateHead=0.000000 ; Percent to rotate drivers head with slip
angle. 0 to 1 with 1 being 100%
326 drivingCamFOV=111.000000 ; driving camera field of view
327 DrivingVanishY=-0.120000 ; Shift the driving view up/down to make it
easier to see the dash.
328 virtualMirrorFOV=120.000000 ; virtual mirror field of view
329
330 [XXX Dev Use Only]
331 AutoCPUMeter=1 ; Force the C meter on if it seems like
Skew is being induced by an overtaxed BG?

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```
332 CPUMeter=0 ; Include the sim-thread's CPU usage in the
    L/Q/S meter group?
333 CPUMeterAsText=0 ; Show CPU meter as ms in text?
334 dbgTextBG= ; r,g,b[,a]
335 dbgTextFG= ; r,g,b[,a]
336 MaskFPUExceptionsBG=0 ; 1=mask floating point errors (realtime)
337 MaskFPUExceptionsFG=0 ; 1=mask floating point errors (graphics)
338 maxAllowedHangTimeSecondsBG=0 ; 0=disable (realtime)
339 maxAllowedHangTimeSecondsFG=0 ; 0=disable (renderering)
340 xHeight=1600 ;
341 xTilesAcross=1 ; mosaic
342 xWidth=2048 ; must be multiple of 4*xTilesAcross!
343
```